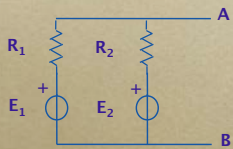


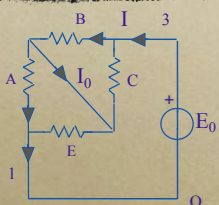
# Esercitazione 11

## Esercizi



Determinare la d.d.p. tra i morsetti A e B

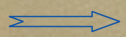
## Ponte in equilibrio



$R_A = 1 \Omega$ ;  
 $R_B = 1 \Omega$ ;  
 $R_C = 3 \Omega$ ;  
 $R_E = 3 \Omega$ ;  
 $R_D = 3 \Omega$ ;  
 $E_0 = 3V$ .

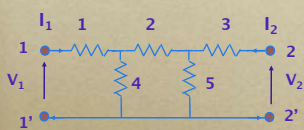
$$I_B = I \frac{R_C}{R_B + R_C}$$

$$I_A = I \frac{R_E}{R_A + R_E}$$



$$R_B R_E = R_A R_C$$

## Esercizi: Matrice delle R e delle G



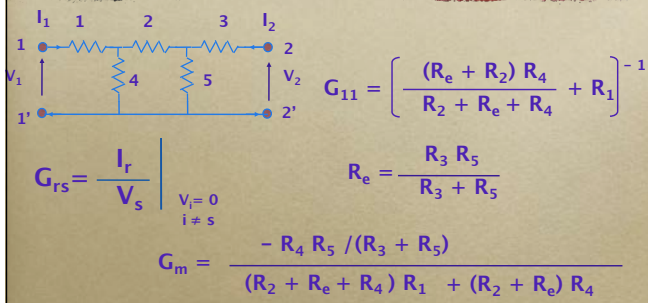
$$R_{11} = \frac{(R_2 + R_5) R_4}{R_2 + R_5 + R_4} + R_1$$

$$R_{22} = \frac{(R_2 + R_4) R_5}{R_2 + R_5 + R_4} + R_3$$

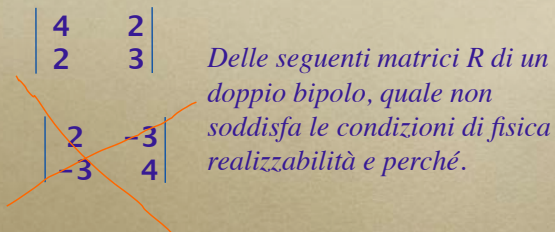
$$R_m = \frac{R_5 R_4}{R_2 + R_5 + R_4}$$

$$R_{rs} = \frac{V_r}{I_s} \quad \left| \begin{array}{l} I_i = 0 \\ i \neq s \end{array} \right.$$

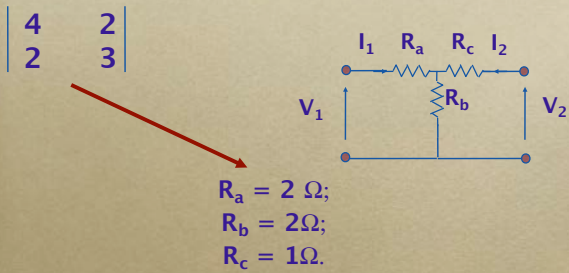
Esercizi:  
Matrice delle R e delle G



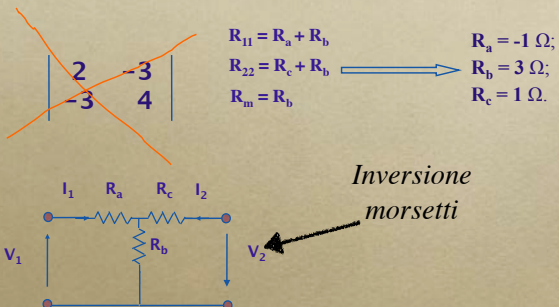
Esercizi:  
Condizioni di fisica realizzabilità



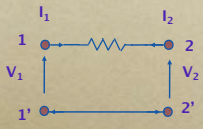
Esercizi:  
Condizioni di fisica realizzabilità



Esercizi:  
Condizioni di fisica realizzabilità

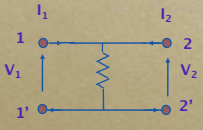


Esercizi:  
Rappresentazioni possibili



$$R_{12} = \frac{V_1}{I_2} \Big|_{I_1=0}$$

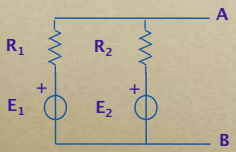
Solo matrice delle G



$$G_{12} = \frac{I_1}{V_2} \Big|_{V_1=0}$$

Solo matrice delle R

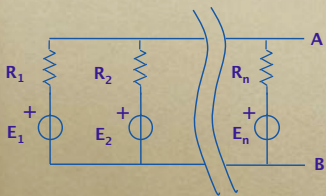
Esercizi:



Determinare la  
d.d.p. tra i morsetti  
A e B

$$V_{AB} = \left[ \frac{E_1}{R_1} + \frac{E_2}{R_2} \right] \frac{R_1 R_2}{R_1 + R_2}$$

Esercizi:



Formula generale?

$$I_r = \frac{E_r - (V_A - V_B)}{R_r} \quad V_A - V_B = \frac{\sum_r \frac{E_r}{R_r}}{\sum_r \frac{1}{R_r}}$$

Esercizi:  
Matrici ibride e di trasmissione

